

# *Modeling Concrete Frames*

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# Key Modeling Parameters

- Stiffness
- Strength
- Stiffness Loss
- Strength Loss
- Deformability – ductility capacity
- Monotonic vs. Cyclic Response
- Rate of Loading
- Robustness of model

# Considerations in Modeling RC Frames

- Materials
  - Confined Concrete
  - Unconfined Concrete
  - Reinforcing Steel
- Sections
  - Elastic Section
  - Uniaxial Section – uncoupled axial & flexure
  - Fiber Section – coupled P-M-M Interaction
- System
  - 2D/3D
  - Rigid/Flexible Diaphragm
- Elements
  - Structural Element
    - Beams – no axial load
    - Columns (P-M Interaction)
  - Plastic-Hinge behavior
    - Confinement
    - Hinge length & growth
    - Yield Penetration
    - Bond Stress/Strength
    - Bar Pull-out, Anchorage loss
    - Bar elongation and buckling
  - Element Type
    - Continuum model
    - Distributed plasticity
    - Lumped plasticity
    - Displacement-based
  - Beam-Column Connections
  - Shear
    - Moment-Shear Interaction
    - Shear-Critical Elements

# Modeling Limitations

- We are modeling 3D elements with 1-D line elements with a 2D cross section
- Basic assumption: PLANE SECTIONS REMAIN PLANE
- We don't have a full understanding, hence no dependable predictive model on flexure & shear interaction
- For design, we can just design around shear, we have to face it for evaluation of older non-ductile existing RC structures
- For many existing structures we don't know exactly what is within the cover
- Quality-control in construction is good enough
- Material properties over time
  - Concrete strength with curing
  - Creep and Fatigue
  - Corrosion in reinforcement

# Understanding Behavior

- Make a personal prediction of expected behavior – use the numerical model to validate your prediction. Iterate until you have agreement.



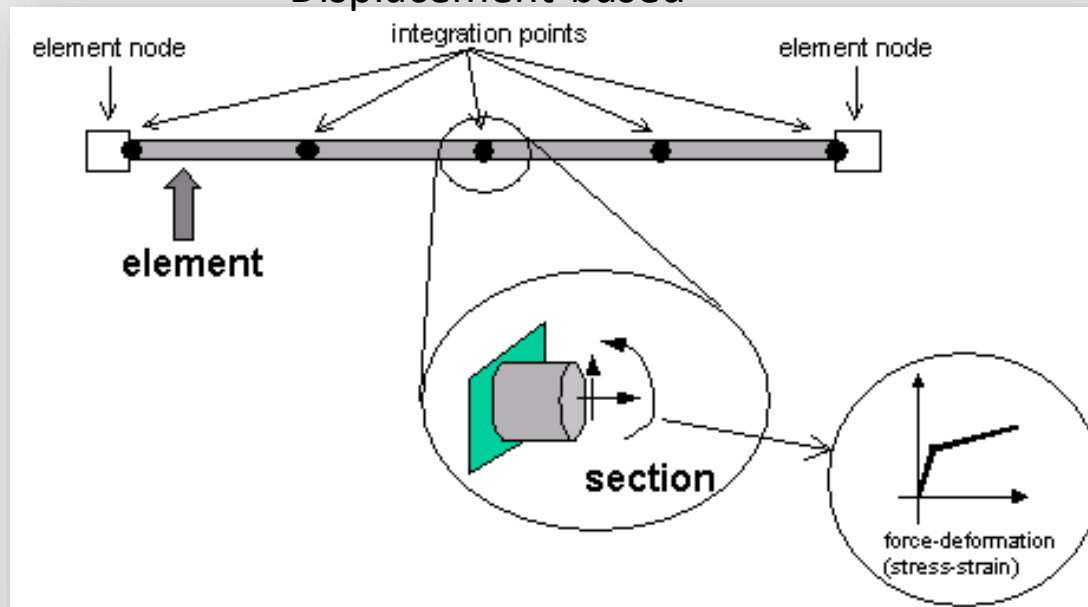
# RC Frames: Beam-Column Elements

## Element Types

Distributed plasticity

Lumped plasticity

Displacement-based



## Sections

Elastic Section

Uniaxial Section – uncoupled axial & flexure

Fiber Section – coupled P-M-M Interaction

## Materials

Confined Concrete

Unconfined Concrete

Reinforcing Steel

All these materials define a force-deformation response

# Uniaxial Materials

## Steel & Reinforcing-Steel Materials

- Steel01 Material
- Steel02 Material
- Hysteretic Material
- Reinforcing Steel Material
- Dodd Restrepo
- RambergOsgoodSteel Material

## Concrete Materials

- Concrete01 Material
- Concrete02 Material
- Concrete04 Material
- Concrete06 Material
- Concrete07
- Concrete01 Material With Stuff in the Cracks
- ConfinedConcrete01 Material

## Standard Uniaxial Materials

- Elastic Uniaxial Material
- Elastic-Perfectly Plastic Material
- Elastic-Perfectly Plastic Gap Material
- Elastic-No Tension Material
- Parallel Material
- Series Material

## Other Uniaxial Materials

- Modified Ibarra-Medina-Krawinkler Deterioration Model with Bilinear Hysteretic Response (Bilin

Material)

- Modified Ibarra-Medina-Krawinkler Deterioration Model with Peak-Oriented Hysteretic Response (ModIMKPeakOriented Material)
- Modified Ibarra-Medina-Krawinkler Deterioration Model with Pinched Hysteretic Response (ModIMKPinching Material)
- BARSLIP Material
- Bond\_SP01
- Fatigue Material
- Hardening Material
- Hyperbolic Gap Material
- Limit State Material
- MinMax Material
- ElasticBilin Material
- ElasticMultiLinear Material
- MultiLinear Material
- Pinching4 Material
- Engineered Cementitious Composites Material
- SelfCentering Material
- Viscous Material
- BoucWen Material
- BWBN Material (Pinching Hysteretic Bouc-Wen Material)
- Pinching Limit State Material

# Uniaxial Materials

Uniaxial materials define a uniaxial force-deformation relationship.

The type of force and deformation depends on where these materials are placed.

- In section fibers, they represent
  - material stress vs. strain
- In uniaxial section, they can represent:
  - force vs. deformation (axial, shear)
  - Bending moment vs. curvature
  - Torsion vs. twist
- In spring elements:
  - Force vs. Deformation
  - Moment vs. Rotation



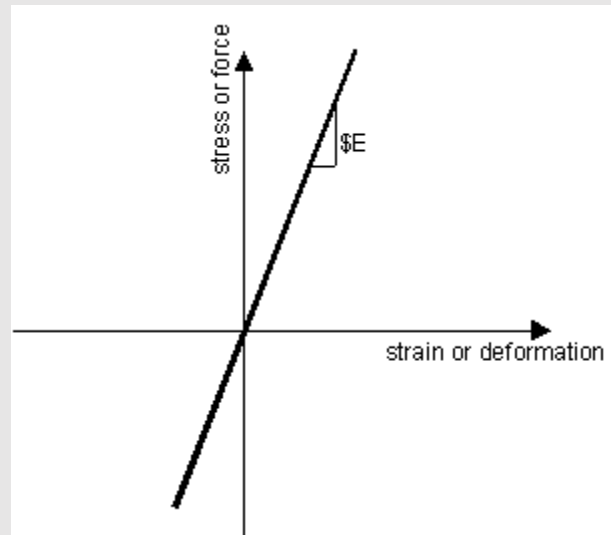
# Elastic Material

**uniaxialMaterial Elastic \$matTag \$E <\$eta>**

**\$matTag** unique material object integer tag

**\$E** tangent

**\$eta** damping tangent (optional,  
default=0.0)

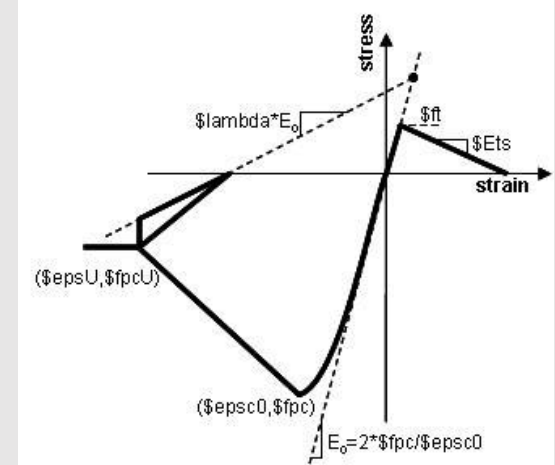


# Concrete

- Concrete01 Material -- Zero Tensile Strength
- **Concrete02 Material -- Linear Tension Softening**
- Concrete04 Material -- Popovics Concrete Material
- Concrete06 Material
- Concrete07 – Chang & Mander’s 1994 Concrete Model
- Concrete01 Material With Stuff in the Cracks
- ConfinedConcrete01 Material

**uniaxialMaterial Concrete02 \$matTag \$fpc \$epsc0 \$fpcu \$epsU \$lambda \$ft \$Ets**

<b>\$matTag</b>	integer tag identifying material
<b>\$fpc</b>	concrete compressive strength at 28 days (compression is negative)*
<b>\$epsc0</b>	concrete strain at maximum strength*
<b>\$fpcu</b>	concrete crushing strength *
<b>\$epsU</b>	concrete strain at crushing strength*
<b>\$lambda</b>	ratio between unloading slope at \$epsU and initial slope
<b>\$ft</b>	tensile strength
<b>\$Ets</b>	tension softening stiffness (absolute value) (slope of the linear tension softening branch)

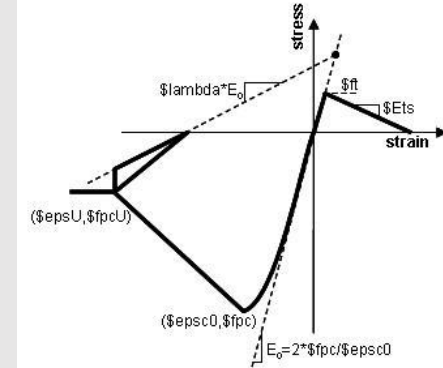


*For a large structure with deformations well beyond the elastic limit, Concrete01 may be enough*

# Confined & Unconfined Concrete

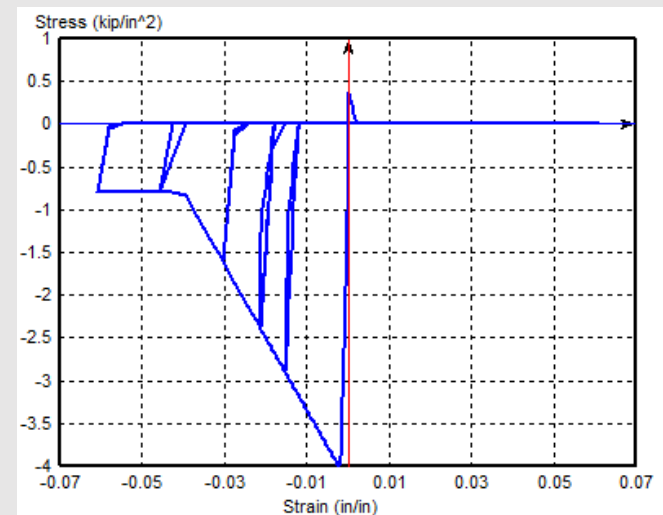
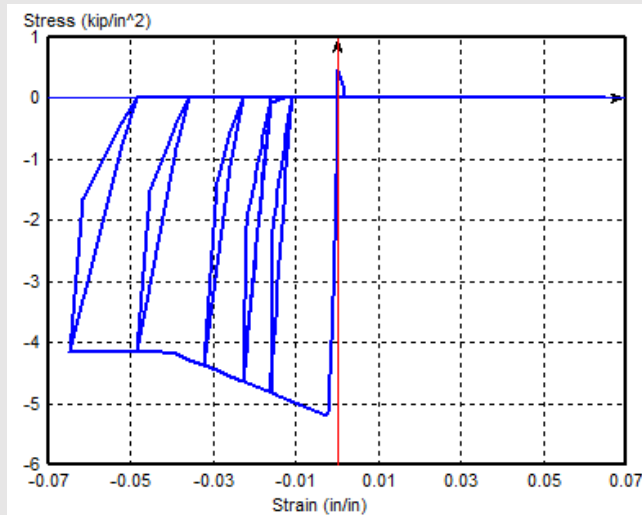
**uniaxialMaterial Concrete02 \$matTag \$fpc \$epsC0 \$fpcu \$epsU \$lambda \$ft \$Ets**

- \$matTag** integer tag identifying material
- \$fpc** concrete compressive strength at 28 days (compression is negative)\*
- \$epsC0** concrete strain at maximum strength\*
- \$fpcu** concrete crushing strength \*
- \$epsU** concrete strain at crushing strength\*
- \$lambda** ratio between unloading slope at \$epsC0 and initial slope
- \$ft** tensile strength
- \$Ets** tension softening stiffness (absolute value) (slope of the linear tension softening branch)



uniaxialMaterial Concrete02 1 -5.2 -0.0025 -4.16 -0.04 0.1 0.52 260.0

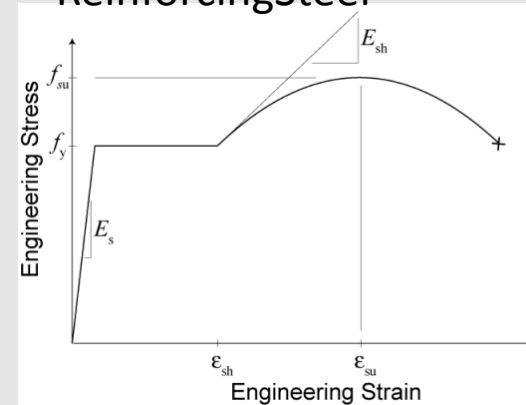
uniaxialMaterial Concrete02 2 -4.0 -0.0022 -0.8 -0.04 0.1 0.4 200.0



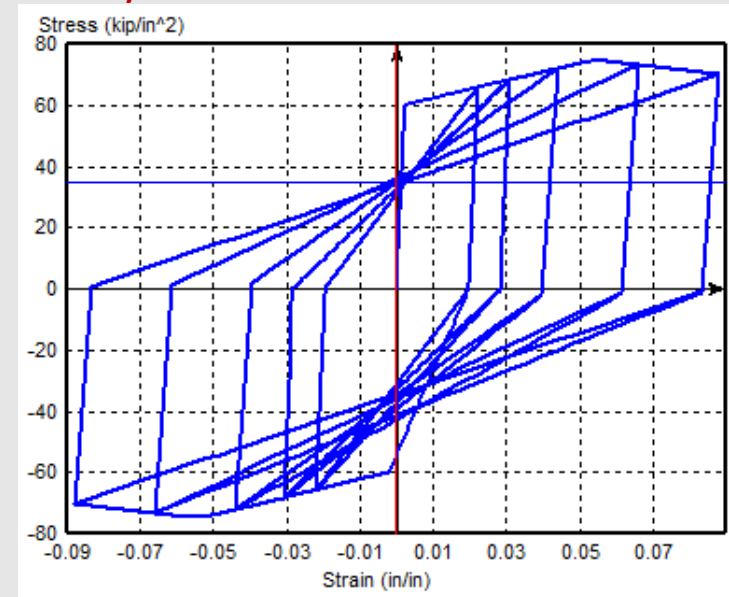
# Reinforcing Steel Materials

- Steel01 Material
- Steel02 Material
- **Hysteretic Material**
- Reinforcing Steel Material
- Dodd Restrepo
- RambergOsgoodSteel Material

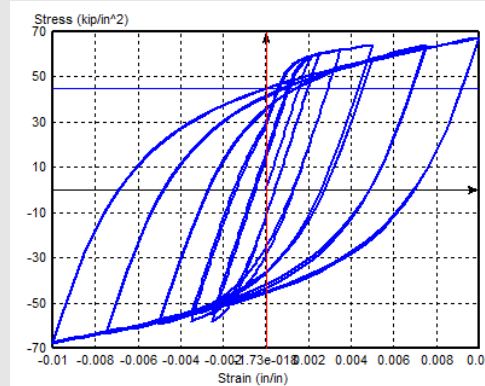
ReinforcingSteel



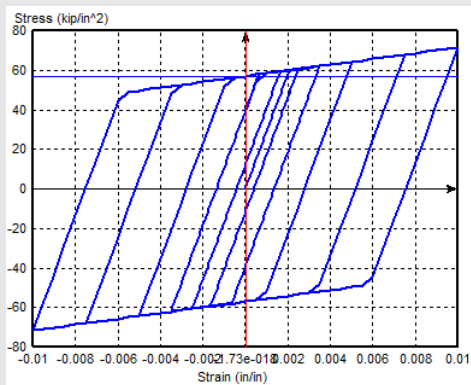
**Hysteretic Material**



Steel02 Material

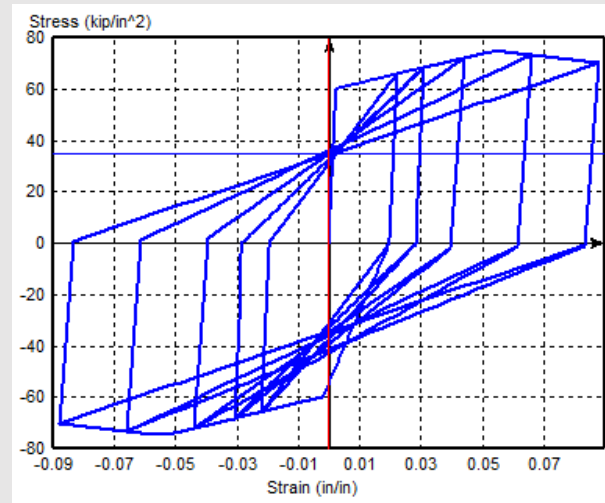
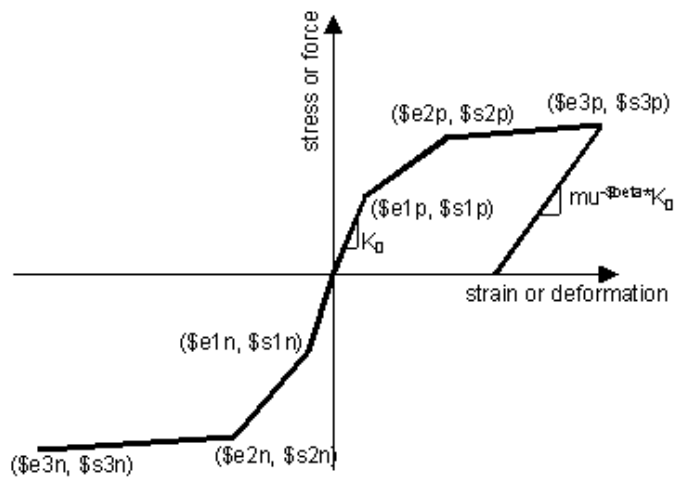


Steel01



# Hysteretic Material

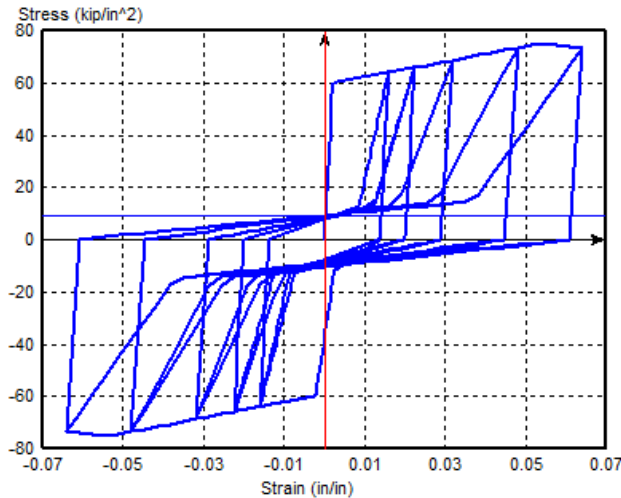
uniaxialMaterial Hysteretic \$matTag \$s1p \$e1p \$s2p \$e2p <\$s3p \$e3p> \$s1n \$e1n  
 \$s2n \$e2n <\$s3n \$e3n> \$pinchX \$pinchY \$damage1 \$damage2 <\$beta>



- Being able to have a negative tangent stiffness at large deformations is useful
- Do not have to have symmetry in tension and compression
- This material can also be used in defining section moment-curvature behavior

# Hysteretic-Material Options

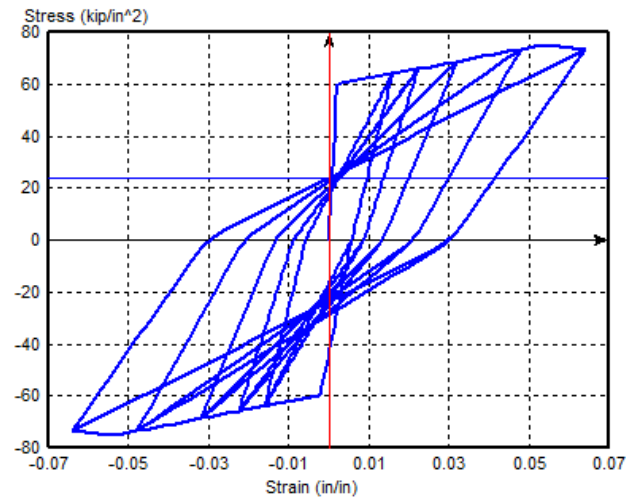
## Material Behavior



## Material Arguments

OpenSees Material : Hysteretic  
Fy = 60  
rFu = 1.25  
K1 = 2.9e+004  
rK2 = 0.01  
rK3 = -0.005  
pinchX = 0.8  
pinchY = 0.2  
damage1 = 0  
damage2 = 0  
beta = 0  
WeightDensity = 0

## Material Behavior



## Material Arguments

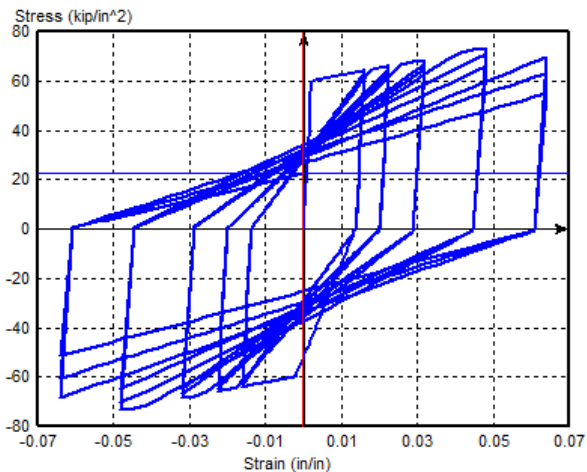
OpenSees Material : Hysteretic  
Fy = 60  
rFu = 1.25  
K1 = 2.9e+004  
rK2 = 0.01  
rK3 = -0.005  
pinchX = 1  
pinchY = 1  
damage1 = 0  
damage2 = 0  
beta = 0.75  
WeightDensity = 0

# Hysteretic Material Damage Parameters

**\$damage1** damage due to ductility:  $D1(\mu-1)$

**\$damage2** damage due to energy:  $D2(E_{ii}/E_{ult})$

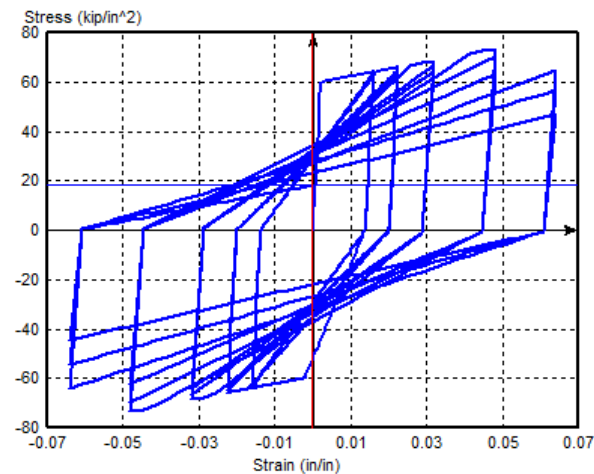
## Material Behavior



## Material Arguments

```
OpenSees Material : Hysteretic
Fy = 60
rFu = 1.25
K1 = 2.9e+004
rK2 = 0.01
rK3 = -0.005
pinchX = 1
pinchY = 1
damage1 = 0.005
damage2 = 0
beta = 0
WeightDensity = 0
```

## Material Behavior



## Material Arguments

```
OpenSees Material : Hysteretic
Fy = 60
rFu = 1.25
K1 = 2.9e+004
rK2 = 0.01
rK3 = -0.005
pinchX = 1
pinchY = 1
damage1 = 0
damage2 = 0.2
beta = 0
WeightDensity = 0
```

# Beam-Column Sections

- Elastic Section
  - linear-elastic moment-curvature relationship
- Uniaxial Section
  - user-defined moment-curvature relationship (use `uniaxialMaterial`)
  - uncoupled P-M and anything else
- Fiber Section
  - user-defined section geometry/materials via fibers
  - coupled P-M interaction
  - coupled bi-directional response
- Section Aggregator
  - combine all uncoupled responses (e.g., Uniaxial flexure + Uniaxial Axial, Fiber flexure/axial + shear)

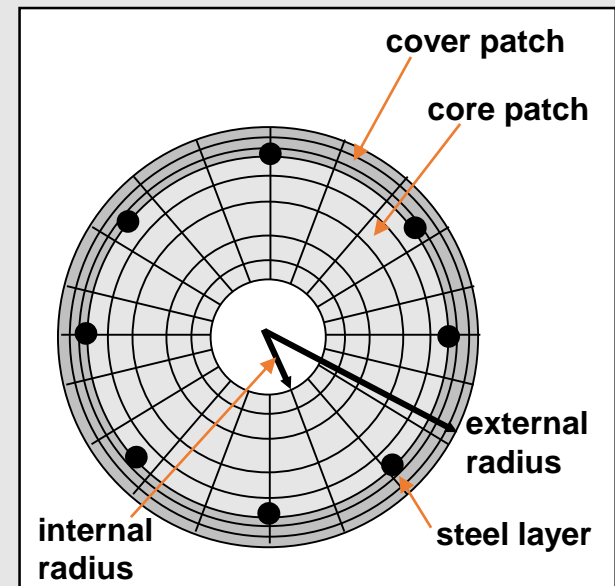
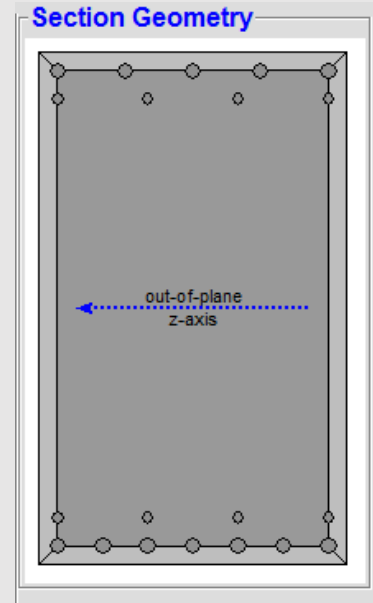


# Fiber Section

```
section Fiber $secTag {  
    fiber <fiber arguments>  
    patch <patch arguments>  
    layer <layer arguments>  
}
```

- User-defined section geometry/materials via fibers
- Coupled P-M interaction
- Coupled bi-directional response
- No shear
- Do not have to compute moment-curvature *a-priori*

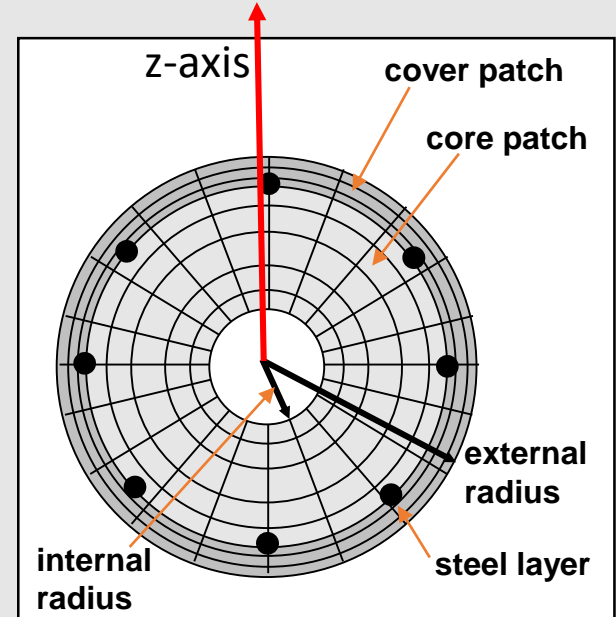
**Note:** You cannot assign this type of section directly to a beam-column element, you need to define behavior for all modes of deformation (axial, bending & shear, for all ndm).



# Fiber Section -- fiber

```
section Fiber $secTag {  
  fiber <fiber arguments>  
  patch <patch arguments>  
  layer <layer arguments>  
}
```

```
fiber $yLoc $zLoc $A $matTag
```



- \$yLoc** y coordinate of the fiber in the section (local coordinate system)
- \$zLoc** z coordinate of the fiber in the section (local coordinate system)
- \$A** area of fiber
- \$matTag** material tag of the pre-defined [uniaxialMaterial](#) object used to represent the stress-strain for the area of the fiber

# Fiber Section -- patch

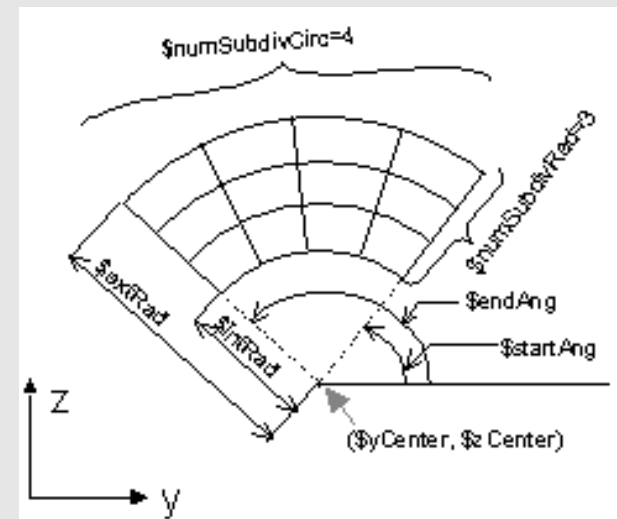
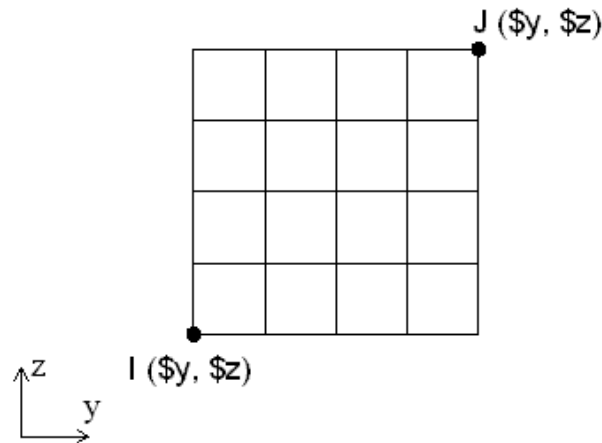
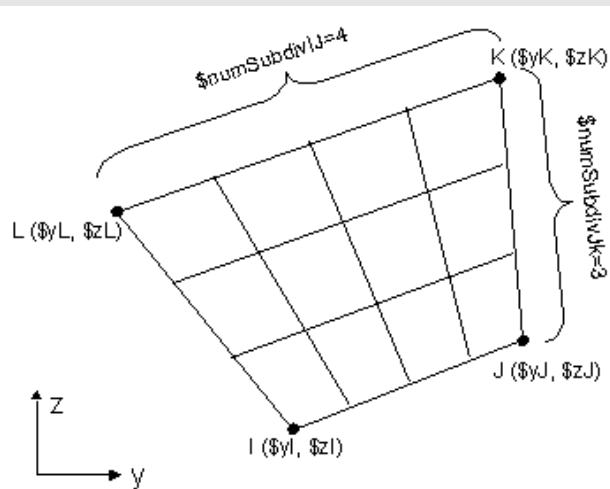
```

section Fiber $secTag {
    fiber <fiber arguments>
    patch <patch arguments>
    layer <layer arguments>
}
    
```

patch rect \$matTag \$numSubdivY \$numSubdivZ \$yI \$zI \$yJ \$zJ

patch quad \$matTag \$numSubdivIJ \$numSubdivJK \$yI \$zI \$yJ \$zJ \$yK \$zK \$yL \$zL

patch circ \$matTag \$numSubdivCirc \$numSubdivRad \$yCenter \$zCenter \$intRad \$extRad <\$startAng \$endAng>

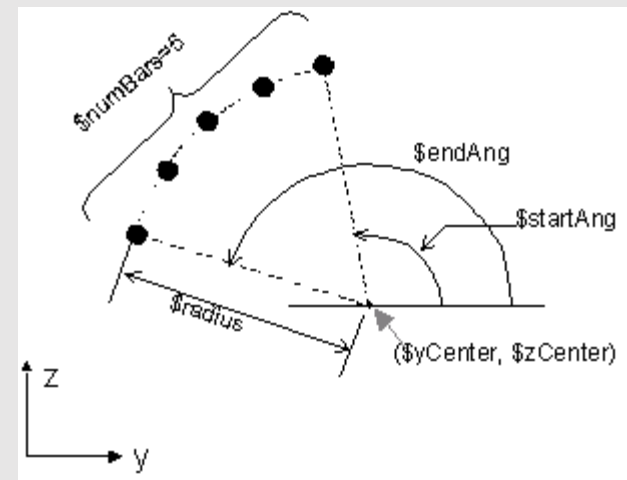
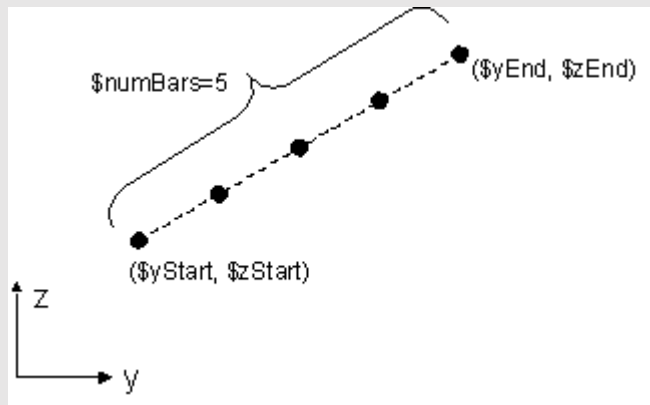


# Fiber Section -- layer

```
section Fiber $secTag {  
    fiber <fiber arguments>  
    patch <patch arguments>  
    layer <layer arguments>  
}
```

layer straight \$matTag \$numFiber \$areaFiber \$yStart \$zStart \$yEnd \$zEnd

layer circ \$matTag \$numFiber \$areaFiber \$yCenter \$zCenter \$radius <\$startAng \$endAng>



# Tcl procedure

A procedure is a function in tcl.

Define procs for a repeated series of commands on a fixed set of input variables

Application: create a procedure to define a fiber section

User: create a library of procedures to use on different projects

Define:

```
proc procName {input variables} {  
    ... series of commands  
}
```

Execute:

```
procName (input variables)
```

Example:

```
proc multiply {a b} {  
    set c [expr $a*$b]  
    return $c  
}  
set a 3; set b 5  
set result [multiply $a $b]
```

# Tcl proc: define rc section

```

proc RCcircSection {id Ri Ro cover coreID coverID steelID Nbars Ab nfCoreR nfCoreT nfCoverR nfCoverT} {
  section fiberSec $id {
    set Rc [expr $Ro-$cover];
    patch circ $coreID $nfCoreT $nfCoreR 0 0 $Ri $Rc 0 360;
    patch circ $coverID $nfCoverT $nfCoverR 0 0 $Rc $Ro 0 360;

    if {$Nbars<= 0} { return }
    set theta [expr 360.0/$Nbars];
    layer circ $steelID $Nbars $Ab 0 0 $Rc $theta 360;
  }
}

```

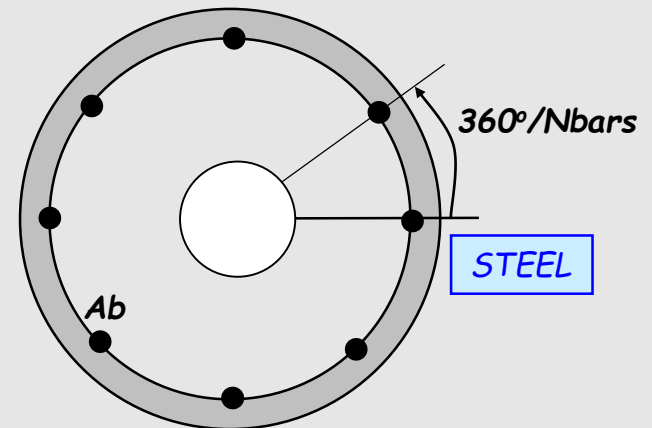
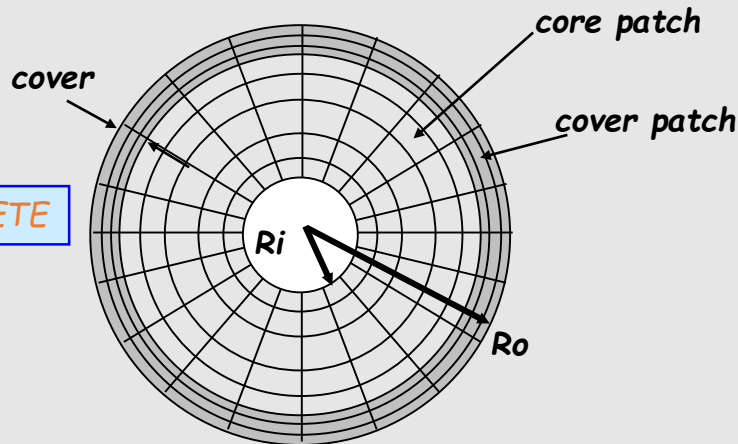
# Core radius

# Define the core patch **CONCRETE**

# Define the cover patch

# angle increment between bars

# Define the reinforcing layer **STEEL**

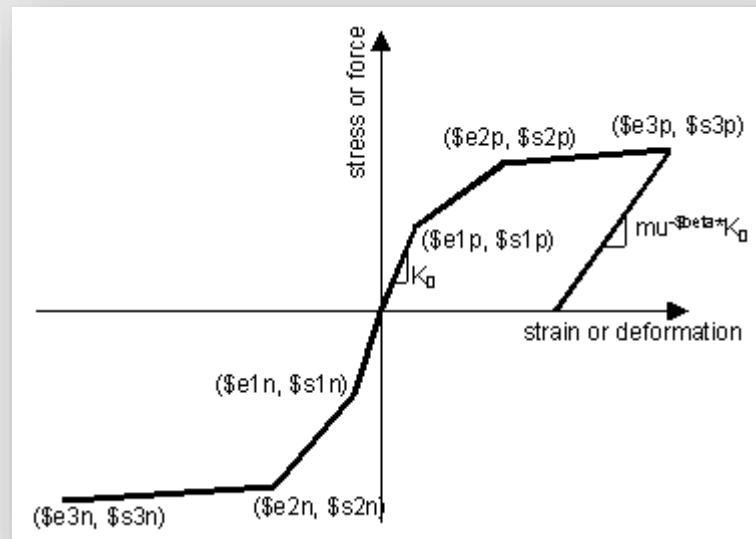


Call:

***RCcircSection \$id \$Ri \$Ro \$cover \$coreID \$coverID \$steelID \$Nbars \$Ab \$nfCoreR \$nfCoreT \$nfCoverR \$nfCoverT***

# Uniaxial Section

- Use uniaxialMaterial to define section **moment-curvature** relationship
  - E.g. Hysteretic Material



**Note:** You cannot assign this type of section directly to a beam-column element, you need to define behavior for all modes of deformation (axial, bending & shear, for all ndm)

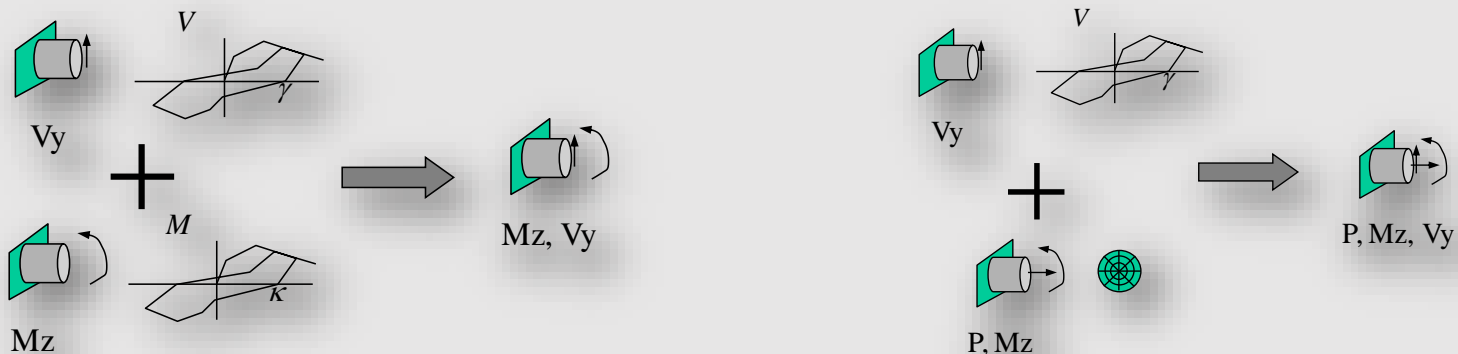
# Section Aggregator

- groups previously-defined section objects (or uniaxialMaterials) into a single section force-deformation model which defines all modes of deformation
- This is the section that gets assigned to the beam-column element

**section Aggregator \$secTag \$matTag1 \$string1 \$matTag2 \$string2 ..... <-section \$sectionTag>**

<b>\$secTag</b>	unique section object integer tag
<b>\$matTag1, \$matTag2 ...</b>	previously-defined <a href="#">uniaxialMaterial</a> objects
<b>\$string1, \$string2 ....</b>	the force-deformation quantities corresponding to each section object. One of the following strings is used:
<b>P</b>	Axial force-deformation
<b>Mz</b>	Moment-curvature about section local z-axis
<b>Vy</b>	Shear force-deformation along section local y-axis
<b>My</b>	Moment-curvature about section local y-axis
<b>Vz</b>	Shear force-deformation along section local z-axis
<b>T</b>	Torsion Force-Deformation

**<-section \$sectionTag>** specifies a previously-defined [Section](#) object (identified by the argument \$sectionTag) to which these [uniaxialMaterial](#) objects may be added to recursively define a new [Section](#) object





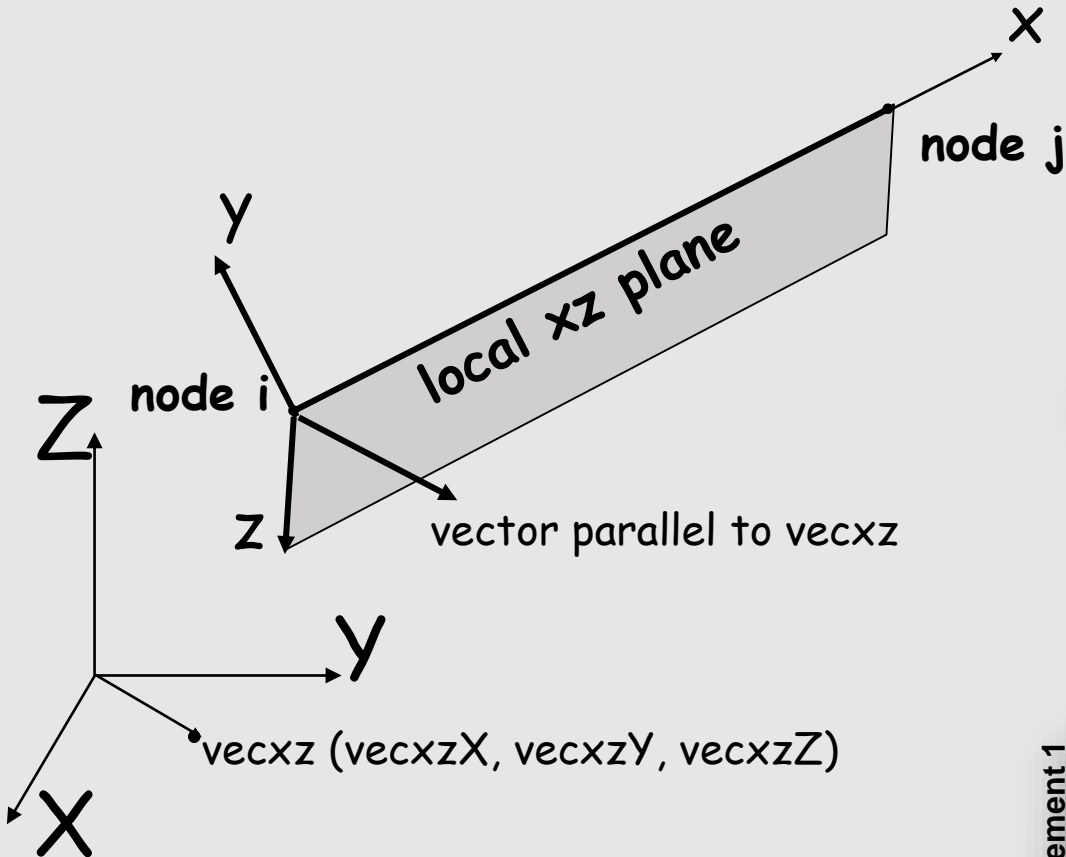
# Geometric transformation

- Performs a linear geometric transformation of beam stiffness and resisting force from the basic system to the global-coordinate system
- Defines rigid offsets
- Defines Geometric nonlinearity

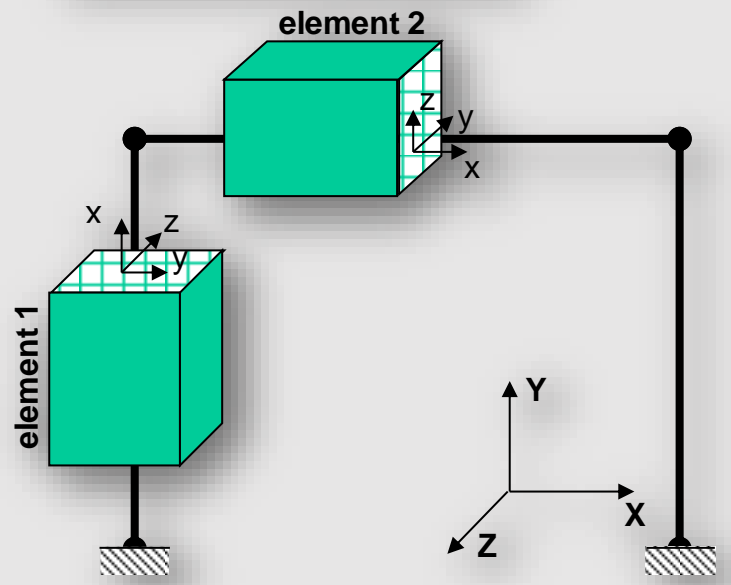
```
geomTransf $Type $transfTag $vecxzX $vecxzY $vecxzZ  
          <-jntOffset $dXi $dYi $dZi $dXj $dYj $dZj>
```

<b>\$Type</b>	Transformation Type: Linear, PDelta or Corotational
<b>\$transfTag</b>	unique identifier for CrdTransf object
<b>\$vecxzX \$vecxzY \$vecxzZ</b>	ONLY IN 3D. X, Y, and Z components of vecxz, the vector used to define the local x-z plane of the local-coordinate system. The local y-axis is defined by taking the cross product of the x-axis and the vecxz vector. These components are specified in the global-coordinate system X,Y,Z and define a vector that is in a plane parallel to the x-z plane of the local-coordinate system. These items need to be specified for the three-dimensional problem.
<b>\$dXi \$dYi \$dZi</b>	joint offset values -- absolute offsets specified with respect to the global coordinate system for element-end node i (the number of arguments depends on the dimensions of the current model) (optional)
<b>\$dXj \$dYj \$dZj</b>	joint offset values -- absolute offsets specified with respect to the global coordinate system for element-end node j (the number of arguments depends on the dimensions of the current model) (optional)

# Local & Global Coordinate Systems



element orientation:



# Beam-Column Elements

- Elastic Beam Column Element
- Elastic Beam Column Element with Stiffness Modifiers
- Beam With Hinges Element
- Displacement-Based Beam-Column Element
- Force-Based Beam-Column Element
- Flexure-Shear Interaction Displacement-Based Beam-Column Element

# Elastic Beam-Column Element

2D

```
element elasticBeamColumn $eleTag $iNode $jNode $A $E $Iz $transfTag
```

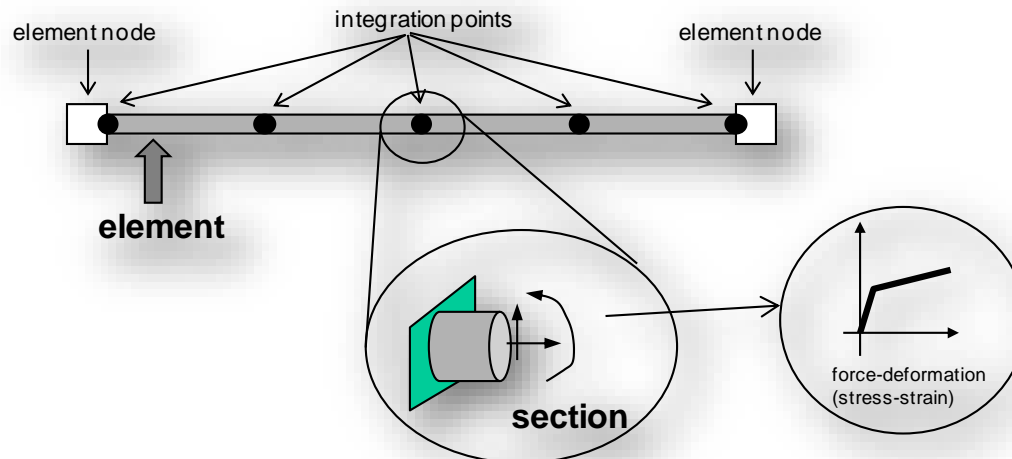
3D

```
element elasticBeamColumn $eleTag $iNode $jNode $A $E $G $J $Iy $Iz $transfTag
```

# Force-Based Beam-Column Element

```
element forceBeamColumn $eleTag $iNode $jNode $transfTag "IntegrationType arg1 arg2 ..."  
    <-mass $massDens> <-iter $maxlters $tol>
```

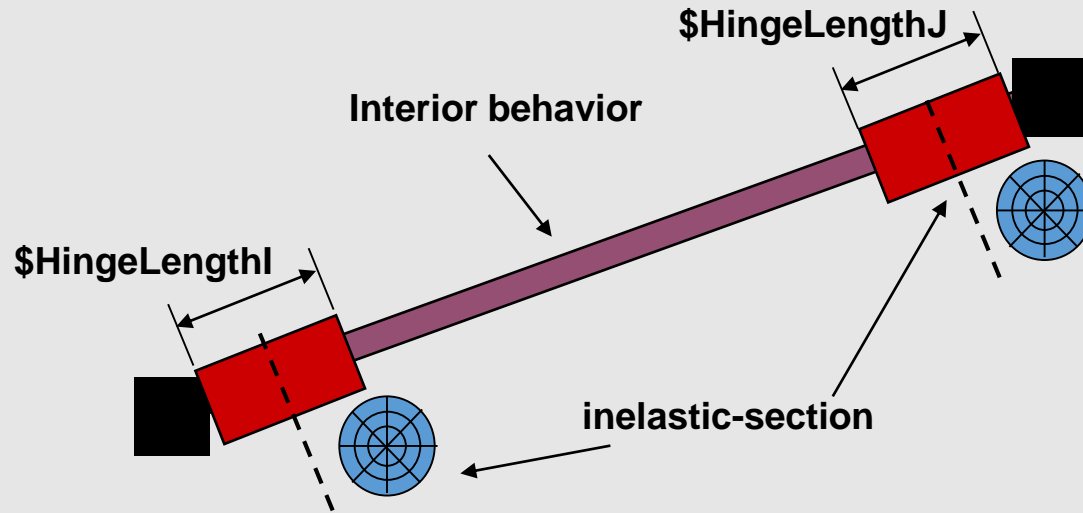
<b>\$eleTag</b>	unique element object tag
<b>\$iNode \$jNode</b>	end nodes
<b>\$transfTag</b>	identifier for previously-defined coordinate-transformation (CrdTransf) object
<b>IntegrationType arg1 arg2 ...</b>	specifies locations and weights of integration points and their associated section force-deformation models (see <a href="#">File:IntegrationTypes.pdf</a> )
<b>\$massDens</b>	element mass density (per unit length), from which a lumped-mass matrix is formed (optional, default=0.0)
<b>\$maxlters</b>	maximum number of iterations to undertake to satisfy element compatibility (optional, default=10)
<b>\$tol</b>	tolerance for satisfaction of element compatibility (optional, default=10-12)



# BeamWithHinges Element

- The original implementation constrained the interior behavior to be elastic.
- Plasticity can now spread beyond the plastic hinge regions
- Hinges can form on the element interior, e.g., due to distributed member loads

```
element forceBeamColumn $eleTag $iNode $jNode $transfTag "HingeRadau $secTagI $LpI  
$secTagJ $LpJ $secTagInterior" <-mass $massDens> <-iter $maxIters $tol>
```



# Example

```
1 # -----
2 # Example4. 2D Portal Frame-- Build Model
3 # nonlinearBeamColumn element, inelastic fiber section
4 # Silvia Mazzoni & Frank McKenna, 2006
5 #
6 # ^y
7 # |
8 # 3 _____ (3) _____ 4
9 # | | |
10 # | | |
11 # | | |
12 # (1) | (2) LCol
13 # | | |
14 # | | |
15 # | | |
16 # =1= | =2= _/_ ----->X
17 # |-----LBeam-----|
18 #
19
20 # SET UP -----
21 wipe; # clear memory of all past model definitions
22 model BasicBuilder -ndm 2 -ndf 3; # Define the model builder, ndm=#dimension, ndf=#dofs
23 set dataDir Data; # set up name of data directory
24 file mkdir $dataDir; # create data directory
25 set GMdir "GMfiles"; # ground-motion file directory
26 source LibUnits.tcl; # define basic and system units
```

# Define units

```
6 # define UNITS -----
7 set in 1.; # define basic units -- output units
8 set kip 1.; # define basic units -- output units
9 set sec 1.; # define basic units -- output units
10 set LunitTXT "inch"; # define basic-unit text for output
11 set FunitTXT "kip"; # define basic-unit text for output
12 set TunitTXT "sec"; # define basic-unit text for output
13 set ft [expr 12.*$in]; # define engineering units
14 set ksi [expr $kip/pow($in,2)];
15 set psi [expr $ksi/1000.];
16 set lbf [expr $psi*$in*$in]; # pounds force
17 set pcf [expr $lbf/pow($ft,3)]; # pounds per cubic foot
18 set psf [expr $lbf/pow($ft,2)]; # pounds per square foot
19 set in2 [expr $in*$in]; # inch^2
20 set in4 [expr $in*$in*$in*$in]; # inch^4
21 set cm [expr $in/2.54]; # centimeter
22 set PI [expr 2*asin(1.0)]; # define constants
23 set g [expr 32.2*$ft/pow($sec,2)]; # gravitational acceleration
24 set Ubig 1.e10; # a really large number
25 set Usmall [expr 1/$Ubig]; # a really small number
```

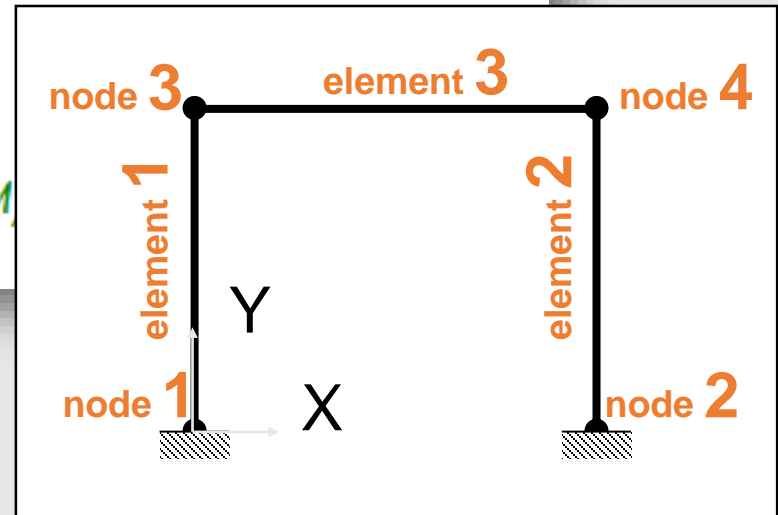


# Example – Geometry, Weight

```
28 # define GEOMETRY -----
29 set LCol [expr 36*$ft];           # column length
30 set LBeam [expr 42*$ft];         # beam length
31 # define section geometry
32 set HCol [expr 5.*$ft];          # Column Depth
33 set BCol [expr 5.*$ft];          # Column Width
34 set HBeam [expr 8.*$ft];         # Beam Depth
35 set BBeam [expr 5.*$ft];         # Beam Width
36 # superstructure weight
37 set Weight [expr 2000.*$kip];
38
39 # calculated parameters
40 set PCol [expr $Weight/2];        # nodal dead-load weight
41 set Mass [expr $PCol/$g];        # nodal mass
42 set MCol [expr 1./12.*($Weight/$LBeam)*pow($LBeam,2)]; # beam-end moment due
43 # calculated geometry parameters
44 set ACol [expr $BCol*$HCol];      # cross-sectional area
45 set ABeam [expr $BBeam*$HBeam];
46 set IzCol [expr 1./12.*$BCol*pow($HCol,3)]; # Column moment of inertia
47 set IzBeam [expr 1./12.*$BBeam*pow($HBeam,3)]; # Beam moment of inertia
```

# Example: Nodes, BC, Mass

```
49 # nodal coordinates:
50 node 1 0 0;          # node#, X, Y
51 node 2 $LBeam 0
52 node 3 0 $LCol
53 node 4 $LBeam $LCol
54 # Single point constraints -- Boundary Conditions
55 fix 1 1 1 0;        # node DX DY RZ
56 fix 2 1 1 0;        # node DX DY RZ
57 fix 3 0 0 0
58 fix 4 0 0 0
59 # nodal masses:
60 mass 3 $Mass 0. 0.; # node#, Mx My
61 mass 4 $Mass 0. 0.
```



# Example: Materials

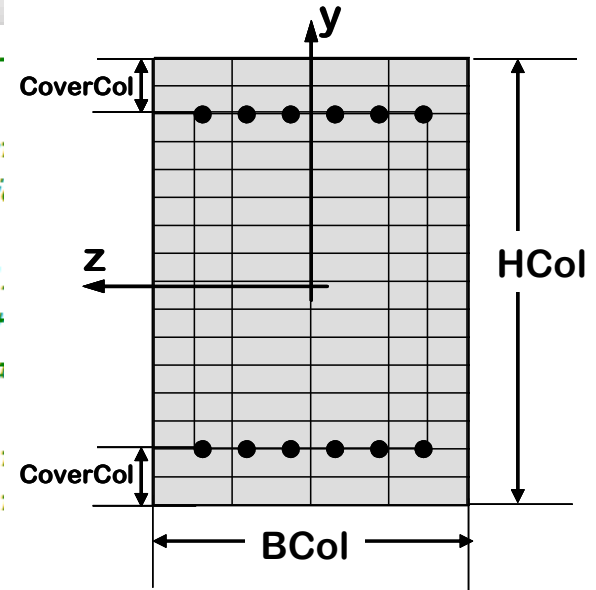
```
64 # MATERIAL parameters -----
65 set IDconcU 1;                # material ID tag -- unconfined cover concrete
66 set IDreinf 2;                # material ID tag -- reinforcement
67 # nominal concrete compressive strength
68 set fc [expr -4.0*$ksi];      # CONCRETE Compressive Strength, ksi (+Tension, -Compression)
69 set Ec [expr 57*$ksi*sqrt(-$fc/$psi)]; # Concrete Elastic Modulus
70 # unconfined concrete
71 set fc1U $fc;                 # UNCONFINED concrete (todeschini parabolic model), maximum stress
72 set eps1U -0.003;            # strain at maximum strength of unconfined concrete
73 set fc2U [expr 0.2*$fc1U];    # ultimate stress
74 set eps2U -0.05;             # strain at ultimate stress
75 set lambda 0.1;              # ratio between unloading slope at $eps2 and initial slope $Ec
76 # tensile-strength properties
77 set ftU [expr -0.14*$fc1U];    # tensile strength +tension
78 set Ets [expr $ftU/0.002];    # tension softening stiffness
79 # -----
80 set Fy [expr 66.8*$ksi];       # STEEL yield stress
81 set Es [expr 29000.*$ksi];    # modulus of steel
82 set Bs 0.01;                 # strain-hardening ratio
83 set RO 18;                   # control the transition from elastic to plastic branches
84 set cR1 0.925;               # control the transition from elastic to plastic branches
85 set cR2 0.15;                # control the transition from elastic to plastic branches
86
87 uniaxialMaterial Concrete02 $IDconcU $fc1U $eps1U $fc2U $eps2U $lambda $ftU $Ets; # build cover concrete
88 uniaxialMaterial Steel02 $IDreinf $Fy $Es $Bs $RO $cR1 $cR2; # build reinforcement material
```

# Example: Column & Beam Sections

```

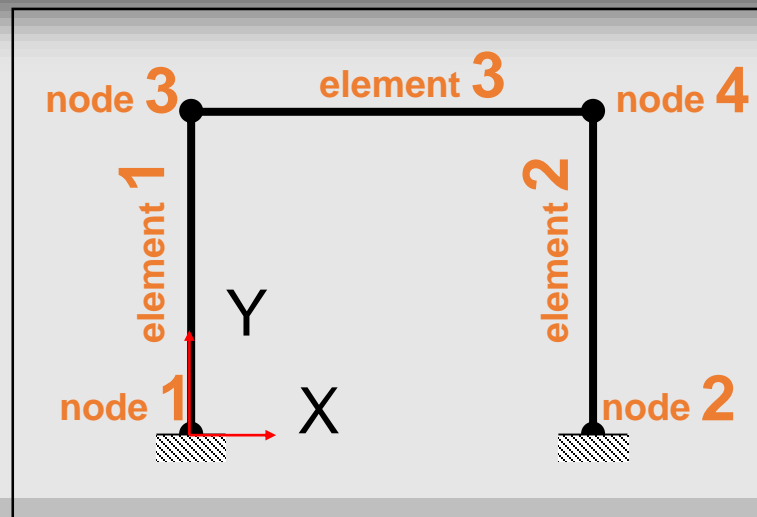
90 # Define ELEMENTS & SECTIONS -----
91 # symmetric section
92 set ColSecTag 1;           # assign a tag number to the column sec:
93 set BeamSecTag 2;         # assign a tag number to the beam secti
94 # define section geometry
95 set coverCol [expr 6.*$in]; # Column cover to reinforcing steel NA.
96 set numBarsCol 10;        # number of longitudinal-reinforcement
97 set barAreaCol [expr 2.25*$in2]; # area of longitudinal-reinforcement ba
98 # RC section:
99 set coverY [expr $HCol/2.0]; # The distance from the section z-axis to :
100 set coverZ [expr $BCol/2.0]; # The distance from the section y-axis to :
101 set coreY [expr $coverY-$coverCol]
102 set coreZ [expr $coverZ-$coverCol]
103 set nfY 16;              # number of fibers for concrete in y-direction
104 set nfZ 4;               # number of fibers for concrete in z-direction
105 section fiberSec $ColSecTag { # Define the fiber section
106   patch quadr $IDconcU $nfZ $nfY -$coverY $coverZ -$coverY -$coverZ $coverY -$coverZ $coverY $coverZ;
107   layer straight $IDreinf $numBarsCol $barAreaCol -$coreY $coreZ -$coreY -$coreZ; # top layer reinforcement
108   layer straight $IDreinf $numBarsCol $barAreaCol $coreY $coreZ $coreY -$coreZ; # bottom layer reinforcement
109 }; # end of fibersection definition
110
111 # BEAM section:
112 section Elastic $BeamSecTag $Ec $ABeam $IzBeam; # elastic beam section

```



# Example: Transformation & Elements

```
114 # define geometric transformation: performs a linear geometric transformation of
115 #   beam stiffness and resisting force from the basic system to the global-coordinate system
116 set ColTransfTag 1;           # associate a tag to column transformation
117 set BeamTransfTag 2;         # associate a tag to beam transformation (good practice to keep col and beam separate)
118 set ColTransfType Linear;     # options, Linear PDelta Corotational
119 geomTransf $ColTransfType $ColTransfTag; # only columns can have PDelta effects (gravity effects)
120 geomTransf Linear $BeamTransfTag;
121
122 # element connectivity:
123 set numIntgrPts 5;           # number of integration points for force-based element
124 element nonlinearBeamColumn 1 1 3 $numIntgrPts $ColSecTag $ColTransfTag; # self-explanatory when using variables
125 element nonlinearBeamColumn 2 2 4 $numIntgrPts $ColSecTag $ColTransfTag;
126 element nonlinearBeamColumn 3 3 4 $numIntgrPts $BeamSecTag $BeamTransfTag;
```



# Example: Recorders

```
128 # Define RECORDERS -----
129 recorder Node -file $dataDir/DFree.out -time -node 3 4 -dof 1 2 3 disp;           # displacements of free node
130 recorder Node -file $dataDir/DBase.out -time -node 1 2 -dof 1 2 3 disp;         # displacements of support node
131 recorder Node -file $dataDir/RBase.out -time -node 1 2 -dof 1 2 3 reaction;     # support reaction
132 recorder Drift -file $dataDir/Drift.out -time -iNode 1 2 -jNode 3 4 -dof 1 -perpDirn 2 ; # lateral drift
133 recorder Element -file $dataDir/FCol.out -time -ele 1 2 globalForce;           # element forces -- column
134 recorder Element -file $dataDir/FBeam.out -time -ele 3 globalForce;           # element forces -- beam
135 recorder Element -file $dataDir/ForceColSec1.out -time -ele 1 2 section 1 force; # Column section forces, column
136 recorder Element -file $dataDir/DefoColSec1.out -time -ele 1 2 section 1 deformation; # section deformation, column
137 recorder Element -file $dataDir/ForceColSec$numIntgrPts.out -time -ele 1 2 section $numIntgrPts force; # section forces, column
138 recorder Element -file $dataDir/DefoColSec$numIntgrPts.out -time -ele 1 2 section $numIntgrPts deformation; # section deformation, column
139 recorder Element -file $dataDir/ForceBeamSec1.out -time -ele 3 section 1 force; # Beam section forces, beam
140 recorder Element -file $dataDir/DefoBeamSec1.out -time -ele 3 section 1 deformation; # section deformation, beam
141 recorder Element -file $dataDir/ForceBeamSec$numIntgrPts.out -time -ele 3 section $numIntgrPts force; # section forces, beam
142 recorder Element -file $dataDir/DefoBeamSec$numIntgrPts.out -time -ele 3 section $numIntgrPts deformation; # section deformation, beam
```

# Considerations in Modeling RC Frames

- ✓ **Materials**
  - Confined Concrete
  - Unconfined Concrete
  - Reinforcing Steel
- ✓ **Sections**
  - Elastic Section
  - Uniaxial Section – uncoupled axial & flexure
  - Fiber Section – coupled P-M-M Interaction
- **System**
  - 2D/3D
  - ➔ • Rigid/Flexible Diaphragm
- **Elements**
  - ✓ **Structural Element**
    - Beams – no axial load
    - Columns (P-M Interaction)
  - ➔ • **Plastic-Hinge behavior**
    - Confinement
    - Hinge length & growth
    - Yield Penetration
    - Bond Stress/Strength
    - Bar Pull-out, Anchorage loss
    - Bar elongation and buckling
  - ✓ **Element Type**
    - Continuum model
    - Distributed plasticity
    - Lumped plasticity
    - Displacement-based
  - ➔ • **Beam-Column Connections**
  - ➔ • **Shear**
    - Moment-Shear Interaction
    - Shear-Critical Elements

# Questions?